# A novel method of unmanned surface vehicle autonomous cruise

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#### Abstract

Purpose — This paper aims to propose a new method for combining global path planning with local path planning, to provide an efficient solution for unmanned surface webside (USV) path planning despite the changeable environment. Path planning is the key issue of USV navigation. A lot of research works were done on the global and local path planning. However, little attention was given to combining global path planning with local path planning.

Design/methodology/approach — A search of shortcut Dijkstra algorithm was used to control the USV in the global path planning. When the USV encounters unknown obstacles, it switches to our modified artificial potential field (APF) algorithm for local path planning. The combinatorial method improves the approach of USV path planning in complex environment.

Findings — The method in this paper offers a solution to the issue of path planning in changeable or unchangeable environment, and was confirmed by simulations and experiments. The USV follows the global path based on the search of shortcut Dijkstra algorithm. Both USV achieves obstacle avoidances in the local region based on the modified APF algorithm after obstacle detection. Both the simulation and experimental results demonstrate that the combinatorial path planning method is more efficient in the complex environment.

Originality/value - This paper proposes a new path planning method for USV in changeable environment. The proposed method is capable of efficient navigation in changeable and unchangeable environment.

Keywords Navigation, Path planning, Autonomous robots, USV, Dijkstra

Paper type Research paper

#### 1. Introduction

Over the past several decades, unmanned surface vehicle technology has been greatly improved with the advance of computer capabilities (Han et al., 2015). It attracted much attention for their ability to perform dangerous and time-consuming missions for military and civilian purposes such as environmental monitoring, survey and inspection of marine structures after natural disasters or large-scale accidents (Murphy et al., 2011).

To perform these missions using unmanned surface vehicle (USV), autonomous navigation is a central capability, as USV can move between a starting point and a target point without human intervention (Tamm and Bucknall, 2013). Robot navigation involves solving the path planning or obstacle avoidance problem to generate a feasible path and to optimize this path with respect to certain criteria (Gu and Cao, 2011; Kim et al., 2014). Obstacle avoidance is consisted of global

obstacle avoidance and local obstacle avoidance, and the problem of autonomous obstacle avoidance has been studied intensively in the past (Markus et al., 2014; Chen et al., 2013).

For local path planning, different algorithms bring different effect of obstacle avoidance in unknown environment. Artificial potential field (APF) is a typical path-planning algorithm for robots (Khatib, 1986). Although it is very suitable for low-level real-time control of robot due to its explicit physical implication and simple mathematical description (Zhang et al., 2010; Shu et al., 2014), there are still some problems in the original algorithm, and some substantial improvements were made. Bacterial potential field, which improves the APF with Bacterial evolutionary algorithm (Meetiel et al., 2015; Byrne et al., 2014; Petris et al., 2012), ensures a feasible, optimal and safe path. For dynamic obstacles, Liu and Bocknall (2015) presented the novel

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## **Unmanned A Novel**

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environmental impacts at all timescales ranging from turbulence to decadal and all spatial scales from device and array scales to shelf sea scales Interdisciplinary Evolution of the Machine Brain Wenfeng Wang, Hengjin Cai, Xiangyang Deng, Chenquang Lu, Limin Zhang, 2021-01-04 This book seeks to interpret connections between the machine brain mind and vision in an alternative way and promote future research into the Interdisciplinary Evolution of Machine Brain IEMB It gathers novel research on IEMB and offers readers a step by step introduction to the theory and algorithms involved including data driven approaches in machine learning monitoring and understanding visual environments using process based perception to expand insights mechanical manufacturing for remote sensing reconciled connections between the machine brain mind and vision and the interdisciplinary evolution of machine intelligence This book is intended for researchers graduate students and engineers in the fields of robotics Artificial Intelligence and brain science as well as anyone who wishes to learn the core theory principles methods algorithms and applications of IEMB Romances of Edward Bulwer Lytton (Lord Lytton) ...: My novel Edward Bulwer Lytton Baron Lytton, 1898 Novels and Romances of Edward Bulwer Lytton Edward Bulwer Lytton Baron Lytton, 1898 **Advances in Maritime Technology and Engineering** Carlos Guedes Soares, Tiago A. Santos, 2024-05-08 Advances in Maritime Technology and Engineering comprises a collection of the papers presented at the 7th International Conference on Maritime Technology and Engineering MARTECH 2024 held in Lisbon Portugal on 14 16 May 2024 This Conference has evolved from the series of biannual national conferences in Portugal which have become an international event reflecting the internationalization of the maritime sector and its activities MARTECH 2024 is the seventh of this new series of biannual conferences This book comprises 142 contributions that were reviewed by an International Scientific Committee Advances in Maritime Technology and Engineering is dedicated to maritime transportation ports as well as maritime safety and reliability It further comprises sections dedicated to ship design cruise ship design and to the structural aspects of ship design such as ultimate strength and composites subsea structures as pipelines and to ship building and ship repair The Proceedings in Marine Technology and Ocean Engineering series is dedicated to the publication of proceedings of peer reviewed international conferences dealing with various aspects of Marine Technology and Ocean Engineering The series includes the proceedings of the following conferences the International Maritime Association of the Mediterranean IMAM conferences the Marine Structures MARSTRUCT conferences the Renewable Energies Offshore RENEW conferences and the Maritime Technology MARTECH conferences The Marine Technology and Ocean Engineering series is also open to new conferences that cover topics on the sustainable exploration of marine resources in various fields such as maritime transport and ports usage of the ocean including coastal areas nautical activities the exploration and exploitation of mineral resources the protection of the marine environment and is resources and risk analysis safety and reliability. The aim of the series is to stimulate advanced education and training through the wide dissemination of the results of scientific research The Novels and Romances of Edward

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any of his contemporaries is studied by scholars from disciplines outside literary studies. The contributors here draw together work from economics colonialism and ethnicity gender studies new historicism liberalism legal studies and politics that convincingly argues for the eminence of Trollope's writings as a vehicle for the theoretical explorations of Victorian culture that currently predominate The essays variously examine imperial and postcolonial themes in the context of economic cultural aesthetic and demographic influences show how gender sensitive readings expose Trollope's critique of capitalism's influence address Trollope and sexuality in the context of gueer studies the law archetypal constructions and classical feminism and offer new approaches to narrative theory through examination of Victorian understandings of male and female psychology Regenia Gagnier's concluding chapter revisits the collection's critical strands and reflects on the implications for future studies of Trollope Fiction as Research Practice Patricia Leavy, 2016-06-16 Patricia Leavy herself both a highly published qualitative researcher and a novelist explores the overlaps and intersections between these two ways of understanding and describing human experience including a methodological introduction and five stories showing these methods in action Geolocation of RF Signals Ilir Progri, 2011-01-15 Geolocation of RF Signals Principles and Simulations offers an overview of the best practices and innovative techniques in the art and science of geolocation over the last twenty years It covers all research and development aspects including theoretical analysis RF signals geolocation techniques key block diagrams and practical principle simulation examples in the frequency band from 100 MHz to 18 GHz or even 60 GHz Starting with RF signals the book progressively examines various signal bands such as VLF LF MF HF VHF UHF L S C X Ku and K and the corresponding geolocation requirements per band and per application to achieve required performance objectives of up to 0o precision Part II follows a step by step approach of RF geolocation techniques and concludes with notes on state of the art geolocation designs as well as advanced features found in signal generator instruments Drawing upon years of practical experience and using numerous examples and illustrative applications Ilir Progri provides a comprehensive introduction to Geolocation of RF Signals and includes hands on real world labs and applications using MATLAB in the areas of RF signals specifications RF geolocation distributed wireless communications networks and RF geolocation Geolocation of RF Signals Principles and Simulations will be of interest to government agency program managers industry professionals and engineers academic researchers faculty and graduate students who are interested in or currently designing developing and deploying innovative geolocation of RF Signal systems

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