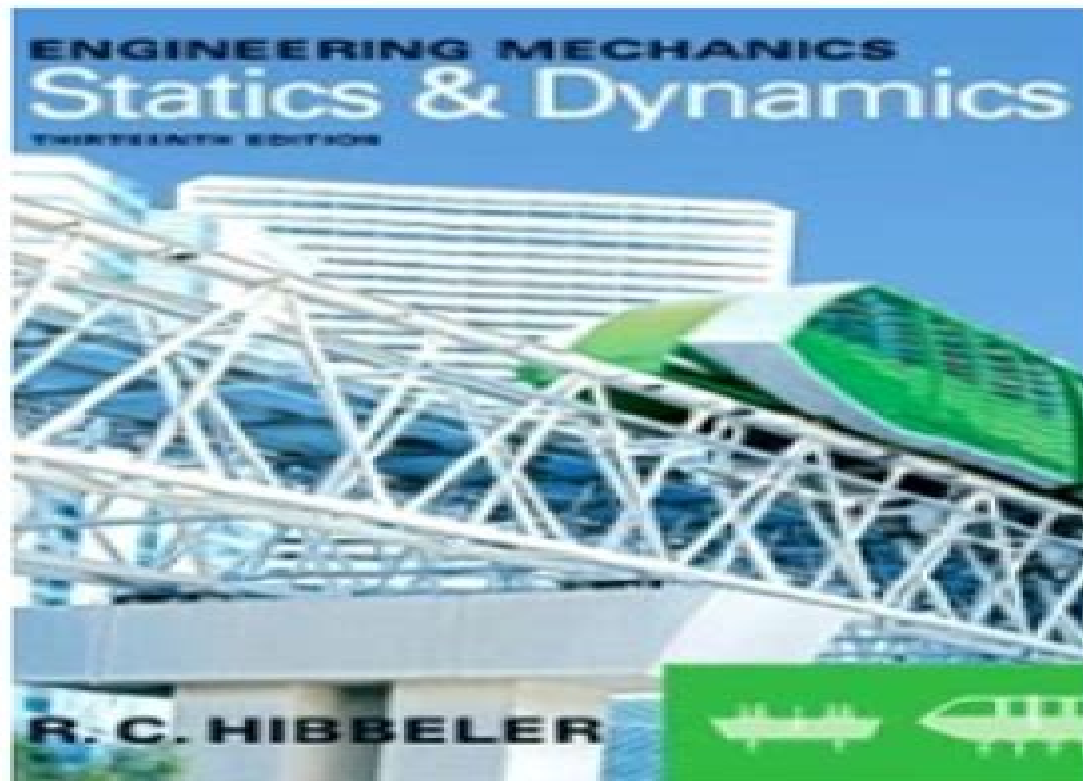




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chapters The most important ones are Chapter 3 includes a mathematical model for the section inertia torques acting on the spinning annulus and thin ring The latter does not have a full solution because the handbooks comprise simplified parameters that cannot be used for an exact solution Chapter 4 offers mathematical model for the arbitrary disposition of the spinning object in space that shows the action of the additional four inertial torques acting on the third axis and new dependencies of gyroscope motions Chapter 7 now presents mathematical model for the gyroscope nutation with a full solution The known mathematical model presents a partial solution due to the complexity of the problem

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