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organizational principle that the central nervous system employs for achieving versatility and adaptability in motor control Recent investigations of muscle synergies motor primitives compositionality basic action concepts and related work in machine learning have contributed to advance at different levels our understanding of the modular architecture underlying rich motor behaviors However the existence and nature of the modules in the control architecture is far from settled For instance regularity and low dimensionality in the motor output are often taken as an indication of modularity but could they simply be a byproduct of optimization and task constraints Moreover what are the relationships between modules at different levels such as muscle synergies kinematic invariants and basic action concepts One important reason for the new interest in understanding modularity in motor control from different viewpoints is the impressive development in cognitive robotics In comparison to animals and humans the motor skills of today s best robots are limited and inflexible However robot technology is maturing to the point at which it can start approximating a reasonable spectrum of isolated perceptual cognitive and motor capabilities. These advances allow researchers to explore how these motor sensory and cognitive functions might be integrated into meaningful architectures and to test their functional limits Such systems provide a new test bed to explore different concepts of modularity and to address the interaction between motor and cognitive processes experimentally Thus the goal of this Research Topic is to review compare and debate theoretical and experimental investigations of the modular organization of the motor control system at different levels By bringing together researchers seeking to understand the building blocks for coordinating many muscles for planning endpoint and joint trajectories and for representing motor and behavioral actions in memory we aim at promoting new interactions between often disconnected research areas and approaches and at providing a broad perspective on the idea of modularity in motor control We welcome original research methodological theoretical review and perspective contributions from behavioral system and computational motor neuroscience research cognitive psychology and cognitive robotics Subject Catalog, 1977 Library of Congress, 1977

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