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ratios in fixed axis and planetary gear trains using the rolling contact equations is illustrated Finally power and force transmission in machines is covered Static and dynamic cases are analyzed and the author shows how the static solutions can provide approximations for the dynamic problems where inertia effects are not significant low inertia and low accelerations Application of matrix algebra for solving the system of equations of equilibrium in statics or equations of motion in dynamics is also illustrated Because of the importance of balancing in any application involving rotating machinery static and dynamic balancing are analyzed The book concludes with a brief coverage of three dimensional dynamics including Euler s equations and gyroscopic effect Aimed at engineering students interested in machine dynamics across a range of disciplines the book is also ideal as a reference for practicing engineers with a good understanding of statics dynamics and matrix algebra

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mechanical systems with many of the problems referring explicitly to design considerations *Intelligent Robotics and Applications* Jangmyung Lee, Min Cheol Lee, Honghai Liu, Jee-Hwan Ryu, 2013-08-23 This two volume set LNAI 8102 and LNAI 8103 constitutes the refereed proceedings of the 6th International Conference on Intelligent Robotics and Applications ICIRA 2013 held in Busan South Korea in September 2013 The 147 revised full papers presented were carefully reviewed and selected from 184 submissions The papers discuss various topics from intelligent robotics automation and mechatronics with particular emphasis on technical challenges associated with varied applications such as biomedical application industrial automation surveillance and sustainable mobility

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